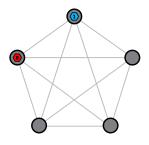
Ohad N. Feldheim

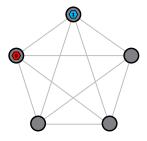
Institute of Mathematics and its Applications, UMN

Jan 2015



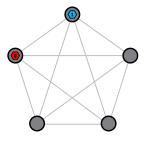
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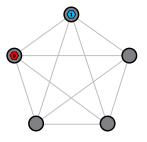
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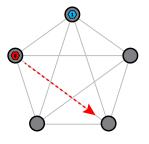
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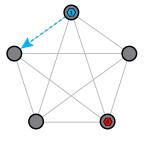
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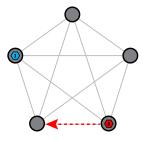
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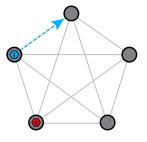
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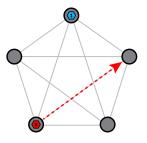
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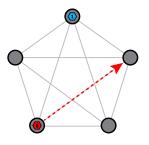
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Q(AHMWW): Given G what is the maximal k for which an avoidance coupling exists?



Terminology

- ullet Sites: $\subset \mathbb{Z}$
- Agents: a_0, \ldots, a_{k-1} .
- "Step": the movement of a single agent.
- "Round": the movement of all agnets.
- t: measures time in terms of rounds.
- K_n : complete graph.
- K_n^* : complete graph with loops.

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• Coupling of random variables X_1, \ldots, X_k is their embedding in a joint probability space Ω .

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- Avoiding collision through scheduling was studied by Winkler, Basu, Sidoravicius and Sly.
- SAC tends to be stronger, thus allows more agents.



Relating a distribution and its marginals

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 ...followed by an industry of obtaining useful information about convex bodies from various projected properties.
- k i.i.d. random walkers on a connected graph always collide.
 The contra-positive of our question is:

When is it impossible for a joint distribution with the same marginals to avoid collision?



Remarks

• Markovian and Hidden Markovian SAC.

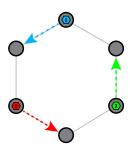
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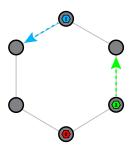
Remarks

- Markovian and Hidden Markovian SAC.
- Discrete time \longleftrightarrow Continuous time poisson.
- In general starting position cannot be assumed uniform.

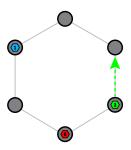
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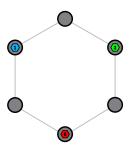
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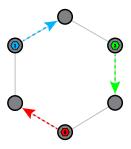
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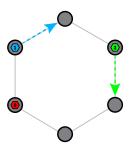
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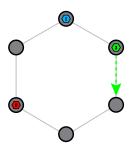
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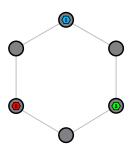
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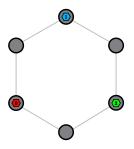


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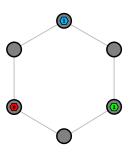
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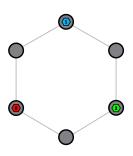
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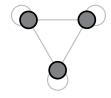
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- The same principle works for $\mathbb{Z}^d/n\mathbb{Z}^d$,



Simple Examples - II - loop triangle

On a K_3^* - maximal SAC is of size 2.

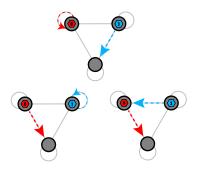


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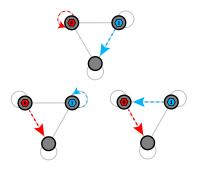
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This walk is:

- minimum-entropy coupling,
- invariant to time reversal.



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Let $n = 2^{d+1}$. There exists a Markovian, minimum-entropy SAC of 2^d agents on K_n^*, K_{n+1}^* and K_{n+1} .

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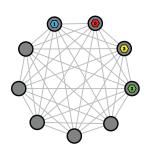
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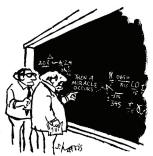
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These couplings are hidden Markovian.



Constructing an Avoidance Coupling on Kzd+1





"I think you should be more explicit here in step two."

Write
$$n = 2^d$$
, $V = \{0, ..., 2n\}$,

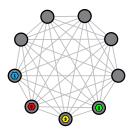
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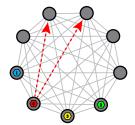
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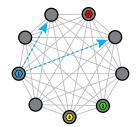
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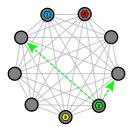
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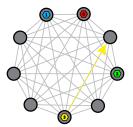
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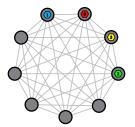
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$$\begin{aligned} a_m(t-1) &\equiv a_n(t-2) + 2^d + \delta_{t-1} + \sum_{i=0}^{d-1} m^i \varepsilon_{t-1}^i 2^i, \\ a_n(t-1) &\equiv a_n(t-2) + 2^d + \delta_{t-1} + \sum_{i=0}^{d-1} 1 \cdot \varepsilon_{t-1}^i 2^i = 0, \\ a_m(t-1) &\equiv \sum_{i=0}^{d-1} (m^i - 1) \varepsilon_{t-1}^i 2^i. \text{ Thus} \\ a_m(t) - a_m(t-1) &\equiv 2^d + \delta_t + \sum_{i=0}^{d-1} m^i \varepsilon_t^i 2^i + \sum_{i=1}^{d-1} (1 - m_{t-1}^i) \varepsilon_{t-1}^i 2^i. \end{aligned}$$

$$a_m(t) = 2^d + \delta_t + \sum_{i=0}^{d-1} m^i \varepsilon_t^i 2^i,$$

$$\begin{split} a_m(t-1) &\equiv a_n(t-2) + 2^d + \delta_{t-1} + \sum_{i=0}^{d-1} m^i \varepsilon_{t-1}^i 2^i, \\ a_n(t-1) &\equiv a_n(t-2) + 2^d + \delta_{t-1} + \sum_{i=0}^{d-1} 1 \cdot \varepsilon_{t-1}^i 2^i = 0, \\ a_m(t-1) &\equiv \sum_{i=0}^{d-1} (m^i - 1) \varepsilon_{t-1}^i 2^i. \text{ Thus} \\ a_m(t) - a_m(t-1) &\equiv 2^d + \delta_t + \sum_{i=0}^{d-1} m^i \varepsilon_t^i 2^i + \sum_{i=1}^{d-1} (1 - m_{t-1}^i) \varepsilon_{t-1}^i 2^i \\ &\equiv 2^d + \delta_t + \sum_{i=0}^{d-1} b^i(t) 2^i \text{ where } b^i \text{ are i.i.d. Bernoulli } \{-1, 1\}, \end{split}$$

$$a_m(t) = 2^d + \delta_t + \sum_{i=0}^{d-1} m^i \varepsilon_t^i 2^i,$$

$$\begin{split} &a_m(t-1) \equiv a_n(t-2) + 2^d + \delta_{t-1} + \sum_{i=0}^{d-1} m^i \varepsilon_{t-1}^i 2^i, \\ &a_n(t-1) \equiv a_n(t-2) + 2^d + \delta_{t-1} + \sum_{i=0}^{d-1} 1 \cdot \varepsilon_{t-1}^i 2^i = 0, \\ &a_m(t-1) \equiv \sum_{i=0}^{d-1} (m^i - 1) \varepsilon_{t-1}^i 2^i. \text{ Thus} \\ &a_m(t) - a_m(t-1) \\ &\equiv 2^d + \delta_t + \sum_{i=0}^{d-1} m^i \varepsilon_t^i 2^i + \sum_{i=1}^{d-1} (1 - m_{t-1}^i) \varepsilon_{t-1}^i 2^i \\ &\equiv 2^d + \delta_t + \sum_{i=0}^{d-1} b^i(t) 2^i \text{ where } b^i \text{ are i.i.d. Bernoulli } \{-1,1\}, \\ &\equiv \text{Unif}\{1 \dots 2^{d+1}\}. \end{split}$$

 $n=2^d$, $V=\{0,\ldots,2^{d+1}\}$, $a_n(t-1)=0$. $m^i:=i$ -th binary digit of m. $\varepsilon_t^0\ldots\varepsilon_t^{d-1}$ uniform $\{-1,1\}$, δ_t uniform $\{0,1\}$.

$$a_m(t) = 2^d + \delta_t + \sum_{i=1}^{d-1} m^i \varepsilon_t^i 2^i, \qquad a_m(t-1) \equiv \sum_{i=1}^{d-1} (m_i - 1) \varepsilon_{t-1}^i 2^i.$$

- No collision in the same round Done.
- Each agent performs simple random walk Done.
- No collisions between rounds

$$a_m(t) = 2^d + \delta_t + \sum_{i=1}^{d-1} m^i \varepsilon_t^i 2^i, \qquad a_m(t-1) \equiv \sum_{i=1}^{d-1} (m_i - 1) \varepsilon_{t-1}^i 2^i.$$

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Let m < q and recall that: $a_q(t-1) \equiv \sum_{i=1}^{d-1} (q_i-1) \varepsilon_{t-1}^i 2^i,$

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Let m < q and recall that: $a_q(t-1) \equiv \sum_{i=1}^{d-1} (q_i-1)\varepsilon_{t-1}^i 2^i$, and thus: $a_m(t) - a_q(t-1) \equiv 2^d + \delta_t + \sum_{i=1}^{d-1} \left[m^i \varepsilon_t^i + (1-q^i)\varepsilon_{t-1}^i \right] 2^i$

 $n=2^d$, $V=\{0,\ldots,2^{d+1}\}$, $a_n(t-1)=0$. $m^i:=i$ -th binary digit of m. $\varepsilon_t^0\ldots\varepsilon_t^{d-1}$ uniform $\{-1,1\}$, δ_t uniform $\{0,1\}$.

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 $n=2^d$, $V=\{0,\ldots,2^{d+1}\}$, $a_n(t-1)=0$. $m^i:=i$ -th binary digit of m. $\varepsilon_t^0\ldots\varepsilon_t^{d-1}$ uniform $\{-1,1\}$, δ_t uniform $\{0,1\}$.

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 $n=2^d$, $V=\{0,\ldots,2^{d+1}\}$, $a_n(t-1)=0$. $m^i:=i$ -th binary digit of m. $\varepsilon_t^0\ldots\varepsilon_t^{d-1}$ uniform $\{-1,1\}$, δ_t uniform $\{0,1\}$.

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$$|\Delta^{i}| \le \begin{cases} 1 & i > k \\ 0 & i = k \\ 2 & i < k \end{cases}$$

 $n=2^d$, $V=\{0,\ldots,2^{d+1}\}$, $a_n(t-1)=0$. $m^i:=i$ -th binary digit of m. $\varepsilon_t^0\ldots\varepsilon_t^{d-1}$ uniform $\{-1,1\}$, δ_t uniform $\{0,1\}$.

$$a_m(t) = 2^d + \delta_t + \sum_{i=1}^{d-1} m^i \varepsilon_t^i 2^i, \quad a_m(t-1) \equiv \sum_{i=1}^{d-1} (m_i - 1) \varepsilon_{t-1}^i 2^i.$$

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Let m < q and recall that: $a_q(t-1) \equiv \sum_{i=1}^{d-1} (q_i-1) \varepsilon_{t-1}^i 2^i,$ and thus: $a_m(t) - a_q(t-1) \equiv 2^d + \delta_t + \sum_{i=1}^{d-1} \left[m^i \varepsilon_t^i + (1-q^i) \varepsilon_{t-1}^i \right] 2^i$ Write $\Delta^i := m^i \varepsilon_t^i + (1-q^i) \varepsilon_{t-1}^i.$ Taking $k = \max_i (m^i \neq q^i),$ we have $m^k = 0, \ q^k = 1,$ and so, $|\Delta^i| \le \begin{cases} 1 & i > k \\ 0 & i = k \\ 2 & i < k \end{cases} \Rightarrow |\delta_t + \sum_{i=1}^{d-1} \Delta^i 2^i| < 1 + \sum_{i=2}^{d-1} 2^i < 2^d$

2^d agents SAC on $K_{2^{d+1}+1}$ - cont.

 $n=2^d$, $V=\{0,\ldots,2^{d+1}\}$, $a_n(t-1)=0$. $m^i:=i$ -th binary digit of m. $\varepsilon_t^0\ldots\varepsilon_t^{d-1}$ uniform $\{-1,1\}$, δ_t uniform $\{0,1\}$.

$$a_m(t) = 2^d + \delta_t + \sum_{i=1}^{d-1} m^i \varepsilon_t^i 2^i, \quad a_m(t-1) \equiv \sum_{i=1}^{d-1} (m_i - 1) \varepsilon_{t-1}^i 2^i.$$

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$$\begin{aligned} |\Delta^{i}| &\leq \begin{cases} 1 & i > k \\ 0 & i = k \Rightarrow |\delta_{t} + \sum_{i=1}^{d-1} \Delta^{i} 2^{i}| < 1 + \sum_{i=2}^{d-1} 2^{i} < 2^{d} \\ 2 & i < k \end{cases} \\ \Rightarrow a_{m}(t) - a_{q}(t-1) \neq 0. \end{aligned}$$

2^d agents SAC on $K_{2^{d+1}+1}$ - cont.

 $n=2^d$, $V=\{0,\ldots,2^{d+1}\}$, $a_n(t-1)=0$. $m^i:=i$ -th binary digit of m. $\varepsilon_t^0\ldots\varepsilon_t^{d-1}$ uniform $\{-1,1\}$, δ_t uniform $\{0,1\}$.

$$a_m(t) = 2^d + \delta_t + \sum_{i=1}^{d-1} m^i \varepsilon_t^i 2^i, \quad a_m(t-1) \equiv \sum_{i=1}^{d-1} (m_i - 1) \varepsilon_{t-1}^i 2^i.$$

Let m < q and recall that: $a_q(t-1) \equiv \sum_{i=1}^{d-1} (q_i-1) \varepsilon_{t-1}^i 2^i$, and thus: $a_m(t) - a_q(t-1) \equiv 2^d + \delta_t + \sum_{i=1}^{d-1} \left[m^i \varepsilon_t^i + (1-q^i) \varepsilon_{t-1}^i \right] 2^i$ Write $\Delta^i := m^i \varepsilon_t^i + (1-q^i) \varepsilon_{t-1}^i$. Taking $k = \max_i (m^i \neq q^i)$, we have $m^k = 0$, $q^k = 1$, and so,

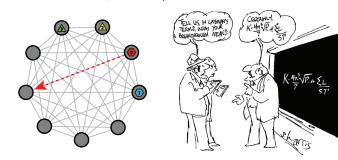
$$\begin{aligned} |\Delta^{i}| &\leq \begin{cases} 1 & i > k \\ 0 & i = k \Rightarrow |\delta_{t} + \sum_{i=1}^{d-1} \Delta^{i} 2^{i}| < 1 + \sum_{i=2}^{d-1} 2^{i} < 2^{d} \\ 2 & i < k \end{cases} \\ &\Rightarrow a_{m}(t) - a_{q}(t-1) \neq 0. \end{aligned}$$

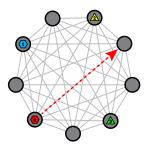
 2^d agents SAC on K_{2^d+1} - cont.

And there is also an applet! (by David Wilson)

http://dbwilson.com/avoidance.svg

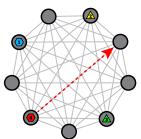
Monotonicity of Avoidance coupling on Kn



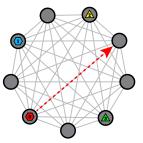


Let G = (V, E) be a finite graph (loops and multi-edges are OK). m agents, a_0, \ldots, a_{m-1} moving on V, are said to form a k-POSAC if:

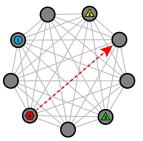
 The agents move one at a time but in changing order,



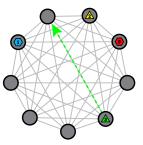
- The agents move one at a time but in changing order,
- Agents a_1, \ldots, a_k are always moving in order,
- The agents never collide



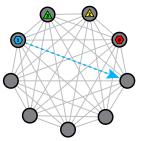
- The agents move one at a time but in changing order,
- Agents a_1, \ldots, a_k are always moving in order,
- The agents never collide
- The path of each agent is a simple random walk.



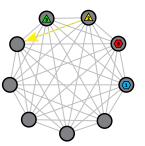
- The agents move one at a time but in changing order,
- Agents a_1, \ldots, a_k are always moving in order,
- The agents never collide
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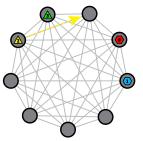
- The agents move one at a time but in changing order,
- Agents a_1, \ldots, a_k are always moving in order,
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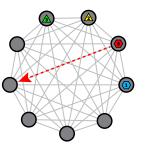
- The agents move one at a time but in changing order,
- Agents a_1, \ldots, a_k are always moving in order,
- The agents never collide
- The path of each agent is a simple random walk.

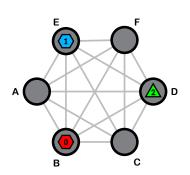


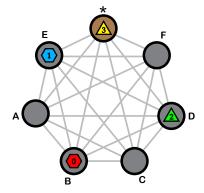
- The agents move one at a time but in changing order,
- Agents a_1, \ldots, a_k are always moving in order,
- The agents never collide
- The path of each agent is a simple random walk.



- The agents move one at a time but in changing order,
- Agents a_1, \ldots, a_k are always moving in order,
- The agents never collide
- The path of each agent is a simple random walk.

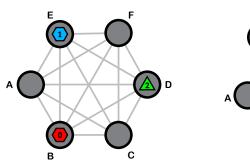


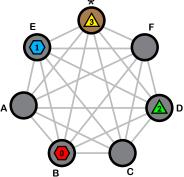


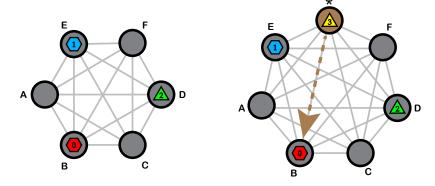


Theorem

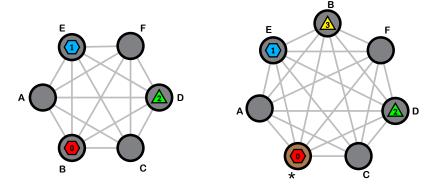
If there is a k-POSAC of m agents on K_n , then there also is a k-POSAC of m+1 agents on K_{n+1} .



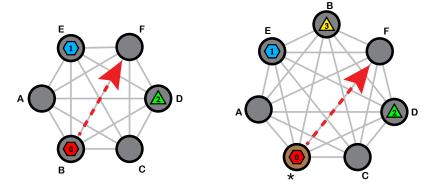




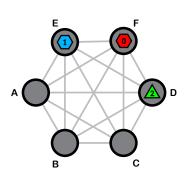
At start of a round flip the special vertex with another vertex.

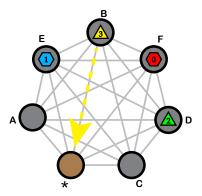


Add a special vertex with a special disordered agent. At start of a round flip the special vertex with another vertex. Continue the process respecting the new labels.



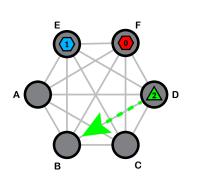
Add a special vertex with a special disordered agent. At start of a round flip the special vertex with another vertex. Continue the process respecting the new labels.

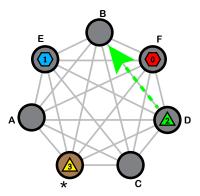




At start of a round flip the special vertex with another vertex.

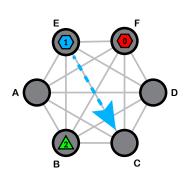
Continue the process respecting the new labels.

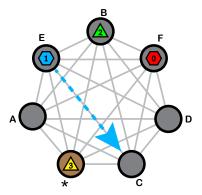




At start of a round flip the special vertex with another vertex.

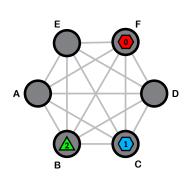
Continue the process respecting the new labels.

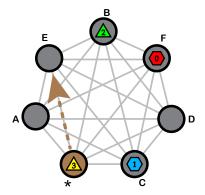




At start of a round flip the special vertex with another vertex.

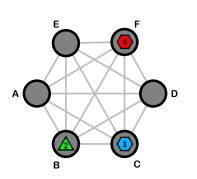
Continue the process respecting the new labels.

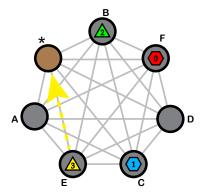




At start of a round flip the special vertex with another vertex.

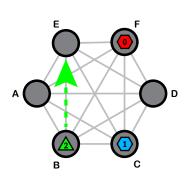
Continue the process respecting the new labels.

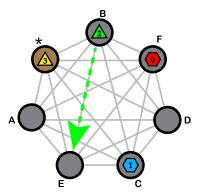




At start of a round flip the special vertex with another vertex.

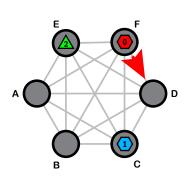
Continue the process respecting the new labels.

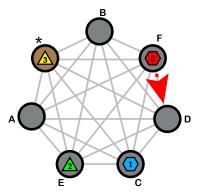




At start of a round flip the special vertex with another vertex.

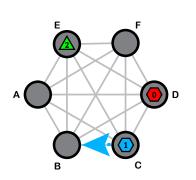
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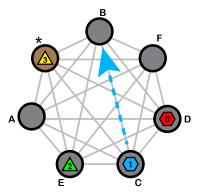




At start of a round flip the special vertex with another vertex.

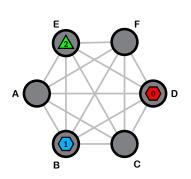
Continue the process respecting the new labels.

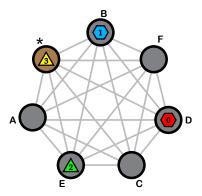




At start of a round flip the special vertex with another vertex.

Continue the process respecting the new labels.

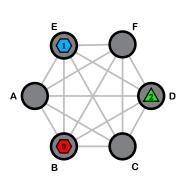


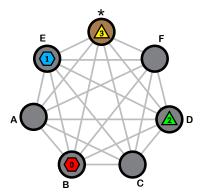


At start of a round flip the special vertex with another vertex.

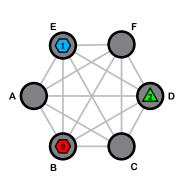
Continue the process respecting the new labels.

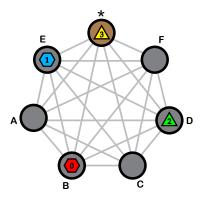
- No collisions occur.
- Each walker makes a simple random walk.



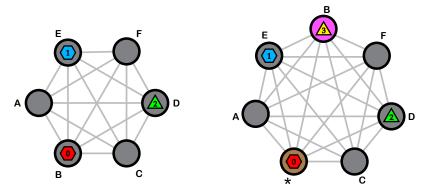


- No collisions occur.
- Each walker makes a simple random walk.



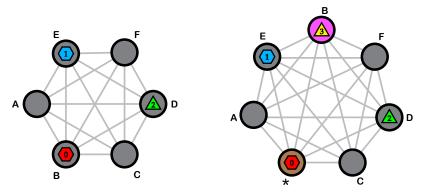


- No collisions occur.
- Each walker makes a simple random walk.

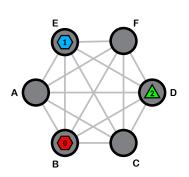


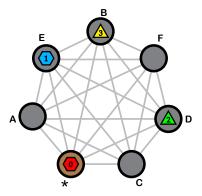
collusion can occur only in the previous * vertex.

- No collisions occur.
- Each walker makes a simple random walk.



collusion can occur only in the previous * vertex. However, it is occupied only as long as the new * vertex is occupied.

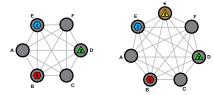




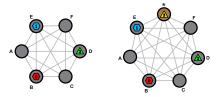
At start of a round flip the special vertex with another vertex.

Continue the process respecting the new labels.

- No collisions occur.
- Each walker makes a simple random walk.

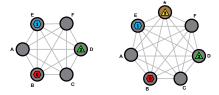


- No collisions occur.
- Each walker makes a simple random walk.



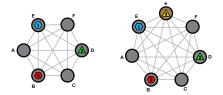
The new agent clearly makes a simple random walk.

- No collisions occur.
- Each walker makes a simple random walk.



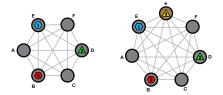
Other agents make a simple random walks on the A-F labels.

- No collisions occur.
- Each walker makes a simple random walk.



Other agents make a simple random walks on the A-F labels. Now suppose an agent is in A at time t, its probability of ending in a vertex currently labeled by B, \ldots, F is:

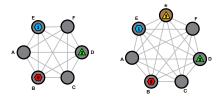
- No collisions occur.
- Each walker makes a simple random walk.



Other agents make a simple random walks on the A-F labels. Now suppose an agent is in A at time t, its probability of ending in a vertex currently labeled by B, \ldots, F is:

 $\mathbb{P}(\text{it moved to that label}) \cdot \mathbb{P}(\text{the label isn't replaced by }*)$

- No collisions occur.
- Each walker makes a simple random walk.



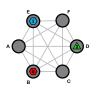
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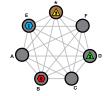
 $\mathbb{P}(\text{it moved to that label}) \cdot \mathbb{P}(\text{the label isn't replaced by }*)$

$$=\frac{1}{n-1}\cdot\frac{n-1}{n}=\frac{1}{n}.$$



- No collisions occur.
- Each walker makes a simple random walk.





Other agents make a simple random walks on the A-F labels. Now suppose an agent is in A at time t, its probability of ending in a vertex currently labeled by B, \ldots, F is:

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$$=\frac{1}{n-1}\cdot\frac{n-1}{n}=\frac{1}{n}.$$

The complementary $\frac{1}{n}$ is the probability of moving to the vertex currently labeled by *.

Open Problems

Open problems

- Upper bound.
- ullet Is $rac{\mathcal{K}_n}{n}
 ightarrow 1?$
- General & random graphs.
- High entropy avoidance coupling.

Thank you!



* all cartoons by Sidney Harris.